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Human Research and Engineering Directorate

Workload and Stress of crews Operating Future Manned Vehicles

Dr. Bruce S. Sterling

Dr. Chuck H. Perala

ARL-HRED Fort Knox Field Element

Overview

Human Research and Engineering Directorate

- Introduction
- Method
- Results
- Discussion
- Recommendations



Introduction

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- Operators of future vehicles must perform many functions with a reduced crew size
- Workload and stress will likely increase
- Examined workload and stress of operators by:
 - -Live versus virtual simulation
 - -Two types of tasks
 - -Autonomous versus standard driving
 - -Driving speed
 - -Two crew positions (driver and gunner)

Method

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Fort Knox Field Element

- Participants were twelve Soldiers comprising four vehicle crews
- Ten participants were either scouts or armor Non-Commissioned Officers or Officers
- Each crew consisted of a vehicle commander, driver, and gunner
- Participants received hands-on training with actual interfaces and controls

Driving

Shooting (including beyond line of sight) Communicating



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- One crew performed in a live environment and three crews performed in a virtual environment
- For live crew driver and gunner in a vehicle and commander (platoon leader) at crew station in a simulator
- All crews conducted missions under two types of threat (enemy RPG teams present or absent)



Method (Continued)

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- •Live crew also conducted missions with autonomous and manual driving; and at two speeds (manual driving only)
- •Measures consisted of :
 - Ratings of workload (NASA TLX)
 - Stress survey (physical and mental)



Method (Continued)

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Advanced Concepts Research Tool (ACRT)



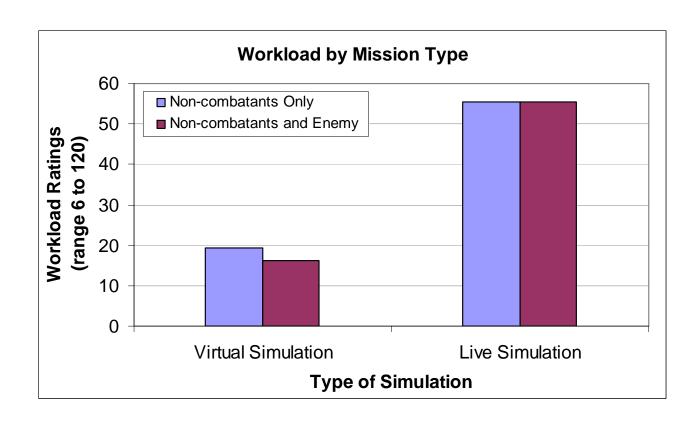
Method (Continued)

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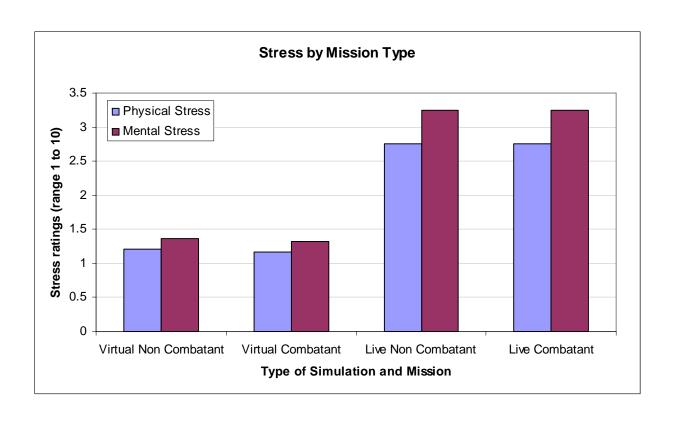
CAT SIL (MCS) crew station

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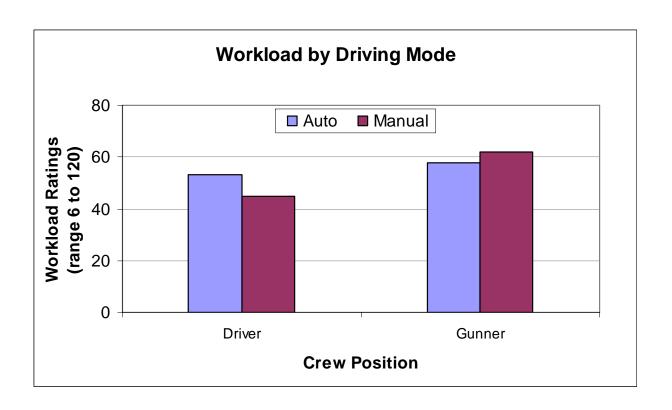


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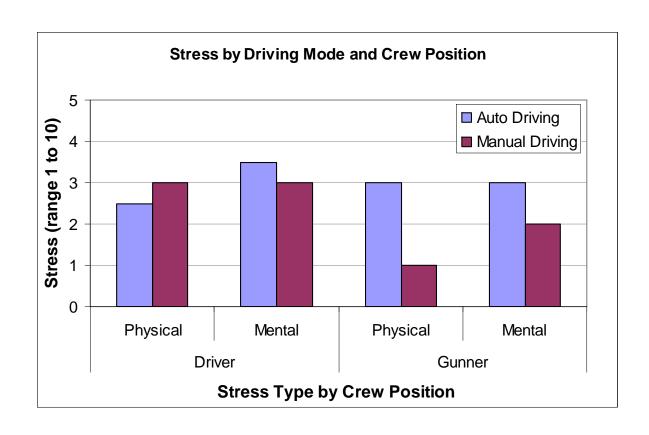


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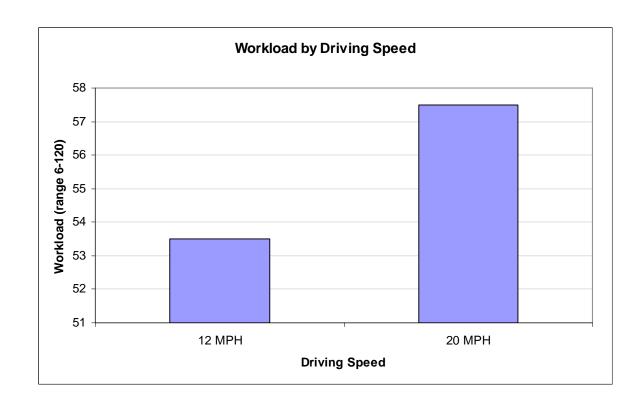


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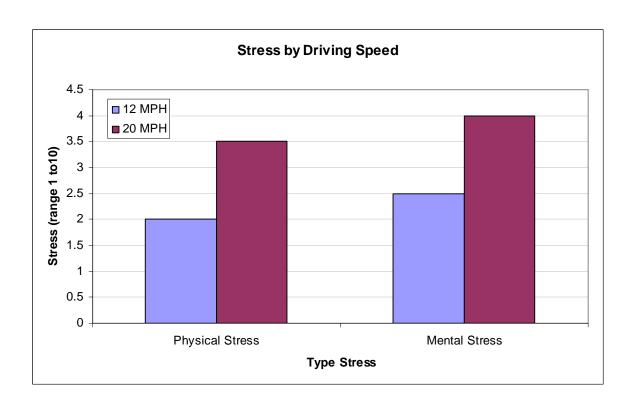


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Discussion

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- Higher workload and stress in live environment likely due to task - Driving
- Not enough differences in two threat conditions to result in different workloads
- Workload and mental stress higher for driver in autonomous mode – perhaps due to requirement to start and stop automatic driving
- Workload and stress higher at higher driving speed



Recommendations

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- Must consider type of task when comparing workload and stress in live and virtual environments
- Missions must differ in types of tasks to differ in workload and stress
- Task automation does not always decrease stress and workload – depends on design of automation
- May need workload reduction at higher speeds – automatic driving?

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Questions?